21	Mechanical En	nergies		
1.	Object / System			
2.	Environment			
3.	Energy (A) Definition (B) Characteristics	(A) Energy is difficult to define. T The object can be in motion (I move (potential).	Think of energy as a characteristic of kinetic), or the object can be in a pos	f a system that allows it to move. sition where releasing it allows it to
	(C) Units	(B)		
		(C)		
4.	Kinetic energy			
5.	Potential energy			
6.	Mechanical Energies	Kinetic Energy	Gravitational Potential Energy	Elastic Potential Energy
	(A) Equation	$K = \frac{1}{2}mv^2$	$U_g = mgh$	$U_s = \frac{1}{2}kx^2$
	(B) Variable	m = mass (kg) v = velocity (m/s)	m = mass (kg) g = accel. of gravity (m/s2) h = height (m)	k = spring constant(N/m) x = stretch (m)
	(C) To possess this energy an object must be/have			
7.	Total Mechanical Energy (A) Define	(A)		
	(B) Equation	(B)		

(A)			
(B)			
(C)			
$h = 4 \text{ m} \qquad 1 \text{ kg}$ $h = 3 \text{ m}$			
h = 2  m $h = 1  m$	1 kg	1 kg	
h = 0 m			1 kg
d with a speed f 60°. It lands ll. How fast is en it hits the			
	(A) (B) (C) h = 4  m 1 kg h = 3  m h = 2  m h = 1  m h = 0  m (C) (C) (C) (C) (C) (C) (C) (C)	(A) (B) (C) h = 4  m. 1  kg h = 3  m. h = 2  m. 1  kg h = 1  m. h = 0  m. (A) (B) (C) (C) (C) (C) (C) (C) (C) (C	(A) (B) (C) h = 4  m. 1  kg h = 3  m. 1  kg h = 2  m. 1  kg h = 1  m. 1  kg h = 0  m. 1  kg h =



22 RESTORING FORCE ANI	) ELASTIC PO	DTENTIAL ENERGY	
<ol> <li>When a spring is stretched or compressed, what two things occur in the spring</li> </ol>	•		
Stretched springs	$m$ $x$ $F_s$ $F$	$x$ $F_s$ $F_g$	$F_g \sin \theta = m$
Compressed springs	m	$ \begin{array}{c}                                     $	$F_g \sin \theta$
14. Hooke's Law $F_s = -kx$ (A) Why is this force known as a " <b>Restoring Force</b> ?" (B) What is the significance of the	(A)		
<ul><li>minus sign?</li><li>(C) What is k?</li><li>(D) When can Hooke's Law be used (for what objects/systems)?</li></ul>	(B)		
	(C)		
	(D)		
15. Elastic Potential Energy $U_s = \frac{1}{2}kx^2$			

16. Phase I Phase II	(A)
$x = 0 \frac{m}{\Delta x_1}$ $x_1 - \frac{m}{\Delta x_2}$ $x_2 - \frac{m}{\Delta x_2}$ $x_2 - \frac{m}{\Delta x_2}$ $x_2 - \frac{m}{\Delta x_2}$ $x_3 - \frac{m}{\Delta x_2}$ $x_4 = 0$ (Equilibrium)	(B) (C)
<ul> <li>A roo g mass is attached to a spring and is lowered</li> <li>25 cm until it reaches equilibrium.</li> <li>(A) Equilibrium is a key phrase. What is its</li> </ul>	(D)
<ul> <li>(B) Determine the spring constant k.</li> <li>(C) Determine the potential energy stored in the spring.</li> <li>(D) Determine the potential energy stored in the</li> </ul>	
<ul> <li><u>spring / mass system</u>.</li> <li>The spring is stretched an additional 10 cm.</li> <li>(E) Determine the energy <u>stored in the spring / mass</u> <u>system</u>.</li> </ul>	(E)
17. A toy gun consists of a spring in a tube that is used to launch a ball horizontally. The spring has a spring constant of 40 N/m and is compressed 20 cm. The ball has a mass of 0.10 kg and is initially at rest. Determine the speed of the ball when it exits the tube.	
18. A 2.0 kg mass is released from rest and moves down the frictionless surface shown below. The quarter circle section has a radius of 3.0 m. At the end of the horizontal surface the mass collides with a spring compressing the spring 40 cm. Determine the spring constant.	

19.WORK AND ENERGYWORK AND FORCEWork Kinetic Energy Theorem: $ W = AK $ A force thru a distance: $W = F_{\parallel}d = Fd \cos\theta$ Changes in kinetic energy are caused by changes in potential energy. Scample: when a ball is dropped the change in height causes a change in potential energy. Scample when a ball is dropped the change in height causes an angual change in kinetic energy resulting in a change in spectral energy: scamper bill to each other are used to solve for work (so $\theta a d   use a change in potential energy.III: speed charges in kinetic energy treating in a change in spectral energy.The components of the force and the displacement so that the scalars quantities representing the vectors are parallel. Distance d can be replaced with \Delta x, \Delta y, or \Delta h.III: speed charges in kinetic energy increases: +W = +\Delta KSign convention: The direction of motion is set as the positive direction in force problems. The sign on force depends on whether force points in the direction of motion or against motion.III: speed increases, kinetic energy decreases: +W = +\Delta KSign convention: The direction of motion or against motion.III: speed increases, kinetic energy decreases: +W = +\Delta KW = F d \cos \thetaIII: the sign on change in potential energy is the opposite of work.W = F d \cos \theta W = \pm L A K = \mp \Delta U W = F d \cos \thetaOr, even  W = \Delta E , where care must be taken with signs.W = E \int d \cos \thetaCurrently we know three mechanical energies. The above generat formulas by modifying the mechanical energy specific formulas by modifying the mechanical energies include a mims sign.K = \frac{1}{2}ms^2 \longrightarrow  W_x = -\Delta(\frac{1}{2}ms^2)  = \frac{1}{2}ms^2 - \frac{1}{2}ms_0^2The work of any force ane be calculated. Determine the component of force that i$	23 WORK		
Work Kinetic Energy Theorem: $  F = \Delta K $ A force thru a distance: $W = F_d = Fd \cos\theta$ Changes in kinetic energy are caused by changes in potential energy. Example: when a ball is dropped the change in height ange in potential energy. Since energy is conserved this causes an equal change in kinetic energy resulting in a change in speed. As a result, the Work Kinetic Energy Theorem can be expanded to include potential energy.The components of the force and the displacement vectors that are parallel to each other are used to solve for work (cos $\theta$ adjusts or the Work Kinetic Energy Theorem can be expanded to include potential energy.The components of the force and the displacement of the trace addition of the control of the order of the potential energy.If $  F = \Delta K = \Delta U $ However; the sign on these variables is important.Sign convention: The direction of motion is set as the positive or work (solve and the sign on the change in potential energy for adjust of work, change in kinetic energy. and change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy formulas $W = F d \cos \theta$ $W = F d cos \theta$ $W = F cos \theta d$ $W = F cos \theta d$ $W = F cos \theta d$ $W = E \pm C A d U$ $W = E \pm C A d U$ $W = E + G cos \theta$ $U_r = wash on change in two work equations by modifying the exclasion in parenthesis and then preceed it with a delta symbol. For potential energys includ$	19.WORK AND ENERGY	WORK AN	ND FORCE
Changes in kinetic energy are caused by changes in potential energy. Example: when a ball is dropped the change in height one provide this causes an aqual change in specific energy is conserved increases, kinetic energy increases: $+W = +AK$ • If speed increases in kinetic energy increases: $+W = +AK$ • If speed increases in kinetic energy increases: $+W = +AK$ • If speed increases is, kinetic energy increases: $+W = +AK$ • If speed increases, kinetic energy increases: $+W = +AK$ • If speed increases, kinetic energy increases: $+W = +AK$ • If speed increases, kinetic energy and vice verse. Example: When a ball falls the speed and kinetic energy and vice verse. Example: When a ball falls the speed and kinetic energy are all equal. However, the sign on these variables to for work, this gift and potential energy is in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy are all equal. However, the sign on change in potential energy is the opposite of work. $\pm W = \pm \Delta K = \pm \Delta U$ Or, even $W = \Delta E$ , where care must be taken with signs. Currently we know three mechanical energies formulas by modifying the equation in parenthesis and then precede if with a delta symbol. For potential energies include a minus sign. $K = \frac{1}{2}mn^2 \longrightarrow [W = \Delta (\frac{1}{2}mr^2)] = \frac{1}{2}mr^2 - \frac{1}{2}mr_0^2$ $U_x = mgh \longrightarrow [W_x = -\Delta (\frac{1}{2}kr^2)] = -(\frac{1}{2}kr^2 - \frac{1}{2}kr_0^2)$ $W = \frac{1}{2}kr^2 \longrightarrow [W_x = -\Delta (\frac{1}{2}kr^2)] = -(\frac{1}{2}kr^2 - \frac{1}{2}kr_0^2)$	<b>Work Kinetic Energy Theorem</b> : $W = \Delta K$	A force thru a distance: $W = R$	$F_{\parallel}d = Fd\cos\theta$
Sign convention: Since work is defined as a change in kinetic energy, the sign on work is the same as the sign on the change in kinetic energy. If speed increases, kinetic energy increases: $+W = +\Delta K$ If speed decreases, kinetic energy increases: $-W = -\Delta K$ What about potential energy? In order for energy to be conserved increases in kinetic energy must be offset by decreases in potential energy and vice versa. Example: When a ball falls the speed and kinetic energy must be offset by decreases in potential energy are all equal. However, the sign on change in potential energies are must be taken with signs. Currently we know three mechanical energies. The above general formula can be used to generate energy specific formulas by modifying the mechanical energy specific formulas by modifying the mechanical energies include a minus sign. $K = \frac{1}{2}mv^2 \longrightarrow W = \Delta(\frac{1}{2}mv^2) = \frac{1}{2}mv^2 - \frac{1}{2}mv_0^2$ $U_x = mgh \longrightarrow W_x = -\Delta(\frac{1}{2}kx^2) = -(\frac{1}{2}kx^2 - \frac{1}{2}kx_0^2)$ $W_x = -(\frac{1}{2}kx^2) + (W_x = -\Delta(\frac{1}{2}kx^2) = -(\frac{1}{2}kx^2 - \frac{1}{2}kx_0^2)$ $W_x = -\frac{1}{2}kx^2$ $W_x = here sign that would$	Changes in kinetic energy are caused by changes in potential energy. Example: when a ball is dropped the change in height causes a change in potential energy. Since energy is conserved this causes an equal change in kinetic energy resulting in a change in speed. As a result, the Work Kinetic Energy Theorem can be expanded to include potential energy. $W = \Delta K = \Delta U$ However, the sign on these variables is important.	The components of the force and are parallel to each other are used the either force or displacement s representing the vectors are paral with $\Delta x$ , $\Delta y$ , or $\Delta h$ . W =	the displacement vectors that d to solve for work ( $\cos \theta$ adjusts to that the scalars quantities lel. Distance <i>d</i> can be replaced $\overline{F_{\parallel}d}$
• If speed increases, kinetic energy increases: $+W = +\Delta K$ • If speed decreases, kinetic energy decreases: $-W = -\Delta K$ What about potential energy? In order for energy to be conserved increases in kinetic energy must be offset by decreases in potential energy, and vice versa. Example: When a ball falls the speed and kinetic energy increase, but height and potential energy decrease. The numerical values of work, change in kinetic energy, and change in potential energy is the opposite of work.	<b>Sign convention</b> : Since work is defined as a change in kinetic energy, the sign on work is the same as the sign on the change in kinetic energy.	<b>Sign convention</b> : The direction of direction in force problems. The whether force points in the direct	of motion is set as the positive sign on force depends on ion of motion or against motion.
Or, even $W = \Delta E$ , where care must be taken with signs. Currently we know three mechanical energies. The above general formula can be used to generate energy specific formulas by modifying the mechanical energy formulas Energy equations can be changed into work equations by enclosing the equation in parenthesis and then precede it with a delta symbol. For potential energies include a minus sign. $K = \frac{1}{2}mv^2 \longrightarrow W = \Delta(\frac{1}{2}mv^2) = \frac{1}{2}mv^2 - \frac{1}{2}mv_0^2$ $U_g = mgh \longrightarrow W_g = -\Delta(mgh) = -(mgh - mgh_0)$ $U_s = \frac{1}{2}kx^2 \longrightarrow W_s = -\Delta(\frac{1}{2}kx^2) = -(\frac{1}{2}kx^2 - \frac{1}{2}kx_0^2)$ $W = \Delta(\frac{1}{2}kx^2) = -(\frac{1}{2}kx^2 - \frac{1}{2}kx_0^2)$ $W = \Delta(\frac{1}{2}kx^2 - \frac{1}{2}kx_0^2)$	• If speed increases, kinetic energy increases: $+W = +\Delta K$ • If speed decreases, kinetic energy decreases: $-W = -\Delta K$ <b>What about potential energy?</b> In order for energy to be conserved increases in kinetic energy must be offset by decreases in potential energy, and vice versa. Example: When a ball falls the speed and kinetic energy increase, but height and potential energy decrease. The numerical values of work, change in kinetic energy, and change in potential energy are all equal. However, the sign on change in potential energy is the opposite of work. $\underline{\pm W = \pm \Delta K = \pm \Delta U}$	F $H$	$F$ $-F$ $m$ $+d$ $W = F d \cos \theta$ $W = F \cos \theta d$ $W = -F_x d$
Energy equations can be changed into work equations by enclosing the equation in parenthesis and then precede it with a delta symbol. For potential energies include a minus sign. $K = \frac{1}{2}mv^2 \longrightarrow W = \Delta\left(\frac{1}{2}mv^2\right) = \frac{1}{2}mv^2 - \frac{1}{2}mv_0^2$ $U_g = mgh \longrightarrow W_g = -\Delta(mgh) = -(mgh - mgh_0)$ $U_s = \frac{1}{2}kx^2 \longrightarrow W_s = -\Delta\left(\frac{1}{2}kx^2\right) = -\left(\frac{1}{2}kx^2 - \frac{1}{2}kx_0^2\right)$ The work of any force can be calculated. Determine the component of displacement that is parallel to the force. $+W_g = \left(-F_g\right)\left(-\Delta h\right)  \text{Moving downward}$ $-W_g = \left(-F_g\right)\left(+\Delta h\right)  \text{Moving upward}$ $-W_f = \left(-f\right)\left(+\Delta x\right)  \text{Work of friction opposes motion}$ $\pm W_{net} = \left(\pm \Sigma F\right)\left(+\Delta r\right)  \text{Net work needs the net force, } \Sigma F$ $F_{\parallel}$ is the same force with the same sign that would	Or, even $W = \Delta E$ , where care must be taken with signs. Currently we know three mechanical energies. The above general formula can be used to generate energy specific formulas by modifying the mechanical energy formulas	$W = \frac{1}{2}$ However, if force lies on an axis (such as motion on an incline), the displacement parallel to force $W$	$\frac{EF_{\parallel} d}{d}$ and displacement is diagonal ten find the component of $= \pm F d_{\parallel}$ .
The definition in particulars and then precede it with a delta symbol. For potential energies include a minus sign. $K = \frac{1}{2}mv^{2} \longrightarrow \qquad W = \Delta\left(\frac{1}{2}mv^{2}\right) = \frac{1}{2}mv^{2} - \frac{1}{2}mv_{0}^{2}$ $U_{g} = mgh \longrightarrow \qquad W_{g} = -\Delta(mgh) = -(mgh - mgh_{0})$ $U_{s} = \frac{1}{2}kx^{2} \longrightarrow \qquad W_{s} = -\Delta\left(\frac{1}{2}kx^{2}\right) = -\left(\frac{1}{2}kx^{2} - \frac{1}{2}kx_{0}^{2}\right)$ $W_{s} = -\Delta\left(\frac{1}{2}kx^{2}\right) = -\left(\frac{1}{2}kx^{2} - \frac{1}{2}kx_{0}^{2}\right)$	Energy equations can be changed into work equations by	The work of any force can be cal	culated. Determine the
$K = \frac{1}{2}mv^{2} \longrightarrow W = \Delta\left(\frac{1}{2}mv^{2}\right) = \frac{1}{2}mv^{2} - \frac{1}{2}mv_{0}^{2} + W_{g} = \left(-F_{g}\right)\left(-\Delta h\right)  \text{Moving downward} + W_{g} = \left(-F_{g}\right)\left(+\Delta h\right)  \text{Moving upward} + W_{g} = \left(-F_{g}\right)\left(+\Delta h\right)  Moving upw$	delta symbol. For potential energies include a minus sign.	component of displacement that is	is parallel to the force.
$U_{s} = \frac{1}{2}kx^{2} \longrightarrow W_{s} = -\Delta\left(\frac{1}{2}kx^{2}\right) = -\left(\frac{1}{2}kx^{2} - \frac{1}{2}kx_{0}^{2}\right) \qquad \pm W_{net} = (\pm \Sigma F)(\pm \Delta r) \text{ Net work needs the net force, } \Sigma F$ $F_{\parallel} \text{ is the same force with the same sign that would}$	$K = \frac{1}{2}mv^{2} \longrightarrow \qquad W = \Delta\left(\frac{1}{2}mv^{2}\right) = \frac{1}{2}mv^{2} - \frac{1}{2}mv_{0}^{2}$ $U_{g} = mgh \longrightarrow \qquad W_{g} = -\Delta\left(mgh\right) = -\left(mgh - mgh_{0}\right)$	$+W_{g} = \left(-F_{g}\right)\left(-\Delta h\right) \qquad Mo$ $-W_{g} = \left(-F_{g}\right)\left(+\Delta h\right) \qquad Mo$ $-W_{f} = \left(-f\right)\left(+\Delta x\right) \qquad Wo$	oving downward oving upward ork of friction opposes motion
$ F_{\parallel} $ is the same force with the same sign that would	$U_s = \frac{1}{2}kx^2 \longrightarrow W_s = -\Delta\left(\frac{1}{2}kx^2\right) = -\left(\frac{1}{2}kx^2 - \frac{1}{2}kx_0^2\right)$	$\pm W_{net} = (\pm \Sigma F) (+\Delta r)  \text{Ne}$	t work needs the net force, $\Sigma F$
Energy is an instantaneous value associated with a specific speed, height, or compression/stretch. Work involves motion, and therefore a change in $F_{\parallel}$ has the same direction as $d$ , then work is nositive When $F_{\parallel}$ and $d$ have opposite	Energy is an instantaneous value associated with a specific speed, height, or compression/stretch. Work involves motion, and therefore a change in	be used in a sum of forces When $F_{\parallel}$ has the same di is positive When $F_{\parallel}$ and	equation. rection as $d$ , then work
speed, height, or compression/stretch.	speed, height, or compression/stretch.	directions, then work is no	egative.

20. A 2.0 kg mass is moving at 20 m/s when it is acted upon by a force in the direction of motion. The force acts over a distance of 30 m, and it increases the speed of the mass to a final speed of 40 m/s. Determine the work done during the period that the force acted (A) using $W = \mathbf{F} \cdot \Delta \mathbf{r}$ (B) Now try Work Kinetic Energy Theorem	(A) (B)
21.	(A)
F	(B)
A 30 N force, $F$ , is applied at an angle of $37^{\circ}$ above the horizontal to a 10 kg mass, as shown above. The mass moves 5.0 m at a constant velocity along a rough horizontal surface	(C)
<ul><li>(A) Determine the work done by the applied force, <i>F</i>.</li><li>(B) Determine the work done by friction.</li></ul>	(D)
<ul><li>(C) Determine the work done by gravity.</li><li>(D) Determine the work done by the normal force.</li><li>(E) Determine the net work</li></ul>	
(E) Determine the net work.	(E)

22.	(A)	(B)
$\Delta d$		
F		
$m \theta$		
	(C)	
F <sub>g</sub>		
¥		
A force, $F$ , is applied to a 3.0 kg mass to push the		
mass a distance,		
$\Delta d = 4.0 \text{ m}$ , up a 30°		
frictionles incline at		
(A) Determine the	(D)	
change in height, $\Delta h$ .		
(B) Determine the		
change in potential		
$\Delta U$ .		
(C) Determine work of		
gravity, $W_g$ , done by		
the force of gravity, $F_{\alpha}$ .	(E)	
(D) Determine the work,		
W, done by the		
applied force, $F$ .		
(E) Determine the net work, $W_{net}$ .		
The 3.0 kg mass is now	(F)	
slides 4.0 m along the		
frictionless 30° incline.		
$\Delta d$	(G)	
$\theta$ V		
(F) Determine the		
change potential		
energy.		
(G) Determine the work done by gravity.	(H)	
(H) Determine the net	()	
work.		



24.	<ul> <li>A 2.0 kg object slides 5.0 m along a rough surface, μ<sub>k</sub> = 0.5.</li> <li>(A) Determine the work of friction if the surface is horizontal.</li> <li>(B) Determine the work of friction if the surface is inclined at 30°.</li> </ul>	(A)
25.	List situations that result in <b>zero work being done by a specific force</b> .	
	-	
26.	List situations that result in <b>zero net work</b> .	
27.	Which force should be used in the formula $W = E d$ to	
	calculate the same value for work that would be obtained using Work Kinetic Energy theorem, $W = \Delta K$ ?	
28.	While the magnitude of work seems straight forward enough, the sign on work seems probelmatic. What is the best way to find the sign? (A) for individual works?	
	(B) for net work?	

	WORK O	F A CONSTANT FORCE	WORK OF A VARIABLE FORCE
29. Graphing work   F     20 N		$\frac{1}{4 \text{ m}}r$	F 12 N 5 m r
(A) Determine work			
(B) Best example of this force?			
(C) How does this relate to the work equation for each force?			
30. Putting it all together		$W = \Delta E = F_{\parallel} \Delta$	$r = Area_{F vs. \Delta r}$
24 WORK AND O	CONSERVAT	TION OF ENERGY	
31. Work Envir	ronment	(A)	
$\begin{array}{c} & \text{System} \\ & & Ug \\ & & & & \\ & & & \\ & & & & & $		(B) Example conservative forces	Non-conservative forces
Conservative Non-Conservative	Forces Act		
<ul> <li>(A) State the key difference between the work of conservative and non- conservative forces.</li> <li>(B) Give an example of each.</li> <li>(C) Does the path taken by an object</li> </ul>		(C) Path, conservative forces	Non-conservative forces
<ul><li>(C) Does the path takes matter?</li><li>(D) Is conservation of o when non-conserva Explain.</li></ul>	energy violated ative forces act?	(C)	I
		(D)	

32. Look at the situation at the very beginning of the problem and access if you see a mass able to	$\sum E_0$	± W	$=$ $\sum E$
move a vertical distance $h$ , a spring that is in a position to stratch or communicate distance $r$ .	0	0	0
and/or a mass that is <u>moving</u> $v$ . Sum these	$mgh_0$	$\pm F_{\parallel}d$	mgh
are none write a zero. Do the same at the end of the problem. Examine the path from start to finish. If you see friction $-W_f$ or a motor $+W$	$\frac{1}{2}kx_0^2$	Friction horizontal $-\mu_k mg \cdot d$	$\frac{1}{2}kx^2$
then apply that to the initial energies. If not leave work as a zero. If you learn new energies or different forms of work add them to the list.	$\frac{1}{2}mv_0^2$	Friction on inclines $-\mu_k mg\cos\theta \cdot d$	$\frac{1}{2}mv^2$
<ol> <li>A mass is sliding to a stop on a rough surface. Determine the distance that the object moves before coming to a stop.</li> </ol>			
34. A mass initially at rest slides down a rough incline. Determine the speed of the object after sliding $x$ meters along the incline.			
35. A 2.0 kg mass starts from rest at the top of a smooth, frictionless, quarter circle slope of radius $r = 3.0$ m. When the mass reaches the bottom of the curve it moves along a horizontal section of track that is rough, $\mu_k = 0.50$ . Determine the horizontal displacement, <i>d</i> , of the mass before coming to rest.			
36. A 0.5 kg mass starts from rest at the top of a smooth, frictionless, quarter circle slope of radius $r = 1.5$ m. When it reaches the bottom of the curve the mass travels 2.0 m on a rough horizontal section, $\mu = 0.35$ . At the end of the track there is a 0.80 m drop. Determine the horizontal displacement, $x$ , during the drop			

25	POWER			
•	Define power. Derive equations for power, and Examine the relationships betw	d state possible units for power. een power, work, force, and time	$\stackrel{\uparrow}{\Rightarrow} \stackrel{\uparrow}{\Rightarrow}$	Solve example problems in this section Complete assignment 130 in the problem set.
37.	Define power			
38.	Equations for power			
39.	Possible units of power			
40.	Exams rarely explicitly say "solve for power." What are some likely wordings for problems that solve for power?			
41.	What strategy should be used to solver for power?			
42.	A kW hr is the unit for what variable?			
43.	A 4.0 kg mass is moved 20 m in 30 s by a 60 N force. <b>Determine the rate that</b> <b>work is being done</b> .			
44.	A 2.0 kg mass is lifted 10 m in 5.0 s. <b>Determine the rate</b> <b>that work is being done</b> .			
45.	A 10 kg block slides 20 meters along a rough surface, that has a coefficient of friction $\mu = 0.3$ , in 30 s. <b>Determine the rate that</b> heat is produced.			
46.	A force of 50 N is applied while moving a mass that is moving at 30 m/s. <b>Determine</b> <b>the rate that energy is</b> <b>supplied to the system.</b>			





49. Determining the change in height of a pendulum	
<ul> <li>50. The sum of force of a pendulum</li> <li>(A) When displaced</li> <li>(B) At equilibrium</li> </ul>	



27	LINEAR MOMENTUM AND IMPULSE				
52.	Momentum: Measure of how difficult it is to stop a moving object. Units: kg•m/s	p = mv			
53.	Impulse: Change in momentum. Units: kg•m/s	$J = F\Delta t = \Delta p$			
		$J = \Delta p = F \Delta t = \text{Area}_{F-t}$			
		$J = m\Delta v = F\Delta t = \operatorname{Area}_{F^{-t}}$			
		$J = m(v - v_0) = F\Delta t = \text{Area}_{F-t}$			
54.	A 5 kg mass initially at 4 m/s speeds up to 7 m/s. What is its impulse?				
55.	A 6 kg mass initially at 3 m/s bounces off a wall. It loses no energy in the collision with the wall, and bounces back at 3 m/s. What is its impulse?				
56.	<ul> <li>A 4 kg mass initially at 5 m/s strikes a wall. The collision with the wall happens at an angle of 53°, as measured from the wall. No energy is lost in the collision.</li> <li>(A) Draw an arrow in the diagram to show the path of the mass after striking the wall.</li> <li>(B) Determine the impulse of the mass.</li> </ul>	(A) 53° (B)			
57.	Determine the final velocity for a 4.0 kg mass originally moving at 2 m/s and experiencing the force graphed.				
58.	Determine the average force that must be applied for 3.0 s to accelerate a 5.0 kg mass from rest to 20 m/s.				
59.	Rearranging the impulse formula yields a famous formula. Which famous formula?				
60.	Total momentum: Often momentum problems involve more than one moving object.	$\Sigma p = m_1 v_1 + m_2 v_2 + \dots$			

28	CONSERVATION OF LINEAR MOMENTUM I				
61.	<b>Conservation of Linear Momentum</b> : The total momentum at the start of a problem must equal the total momentum at the end.	$\Sigma p_0 = \Sigma p$ $m_1 v_{1_0} + m_2 v_{2_0} = m_1 v_1 + m_2 v_2$			
62.	<b>Elastic Collisions</b> (perfectly elastic collisions, totally elastic collisions) are collisions where				
63.	Some examples of these collisions include				
64.	Inelastic Collisions are collisions where				
65.	Kinetic Energy Lost (Dissipated)	$\frac{1}{2}m_1v_{1_0}^2 + \frac{1}{2}m_2v_{2_0}^2 - K_{lost} = \frac{1}{2}m_1v_1^2 + \frac{1}{2}m_2v_2^2$			
	<ul><li>(A) How is kinetic energy lost in a collision?</li><li>(B) Where does the lost energy go and what form of energy does it become?</li></ul>	(A)			
		(B)			
66.	<ul> <li>A mass m<sub>1</sub> = 2 kg moving at 3 m/s to the right collides inelastically with a mass m<sub>2</sub> = 1 kg that is moving at 6 m/s to the left. After the collision mass m<sub>1</sub> is moving at 2 m/s to the left.</li> <li>(A) Determine the total momentum</li> <li>(B) Determine the speed of m<sub>2</sub> after the collision.</li> <li>(C) Determine the Kinetic Energy Lost during the collision.</li> </ul>	(A)			
		(B)			
		(C)			

67.	In <b>perfectly inelastic collisions</b> the colliding objects stick together and kinetic energy is lost.	$m_1 v_{1_0} + m_2 v_{2_0} = (m_1 + m_2) v$
		$\frac{1}{2}m_1v_{1_0}^2 + \frac{1}{2}m_2v_{2_0}^2 - K_{lost} = \frac{1}{2}(m_1 + m_2)v^2$
68.	<ul> <li>A mass m<sub>1</sub> = 1 kg moving at 3 m/s to the right collides perfectly inelastically with a mass m<sub>2</sub> = 4 kg moving at 2 m/s to the left.</li> <li>(A) Determine the speed of the system after the collision.</li> <li>(B) Determine the kinetic energy lost during the collision.</li> </ul>	(A) (B)
69.	<b>Explosion</b> : Opposite of a perfectly elastic collision. Mass starts as one object and then splits into 2 or more objects.	$(m_1 + m_2)v_0 = m_1v_1 + m_2v_2$ When $v_0 = 0$ $0 = m_1v_1 + m_2(-v_2)$ One mass moves right (+) and the other left (-) $m_1v_1 = m_2v_2$ The minus disappears when you rearrange the expression.
70.	A 4 kg mass explodes into two pieces. A 1 kg piece moves to the right at 8 m/s. What is the speed and direction of the other piece?	
29	CONSERVATION OF LINEAR M	OMENTUM II
71.	A 5 kg mass explodes into three pieces. A 1 kg fragment moves in the $-y$ direction at 6 m/s. A 2 kg fragment moves in the $-x$ direction at 4 m/s. Determine the speed and direction of the third fragment.	
	$\begin{array}{c} 4 \text{ m/s} \\ 2 \text{ kg} \\ 1 \text{ kg} \\ 6 \text{ m/s} \end{array}$	





30	<b>CENTER OF MASS</b>				
75.	Center of mass			r <sub>cm</sub>	distance from (0,0) to center of mass (m)
		ľ <sub>cm</sub>	$=\frac{\Sigma mr}{\Sigma m}$	т	mass (kg)
				r	distance from (0,0) to each mass (m)
76.	Determine the center of mass for arrangement. The rod connecting massless and the masses are 2 m $(2 \text{ kg})$	r the following g the masses is apart. 6  kg			
77.	Determine the center of mass for arrangement. Each line on the gr shown below is separated by 1 m perfectly centered at an intersect 2 kg 5 kg 3 kg	r the following rid system n. Each mass is ion of the grids.			
78.	Determine the center of mass for arrangement. The gray squares r of a flat material with uniform d metal. TheEach line on the grid below is separated by 1 m. The square is not known, but is it rea	r the following epresent sheets ensity, such as a system shown mass of each lly needed?			